User-centric solutions for a flexible and modular manufacturing in small and medium-sized shipyard





4th Workshop - AIMEN Technology Center, Spain





The technology



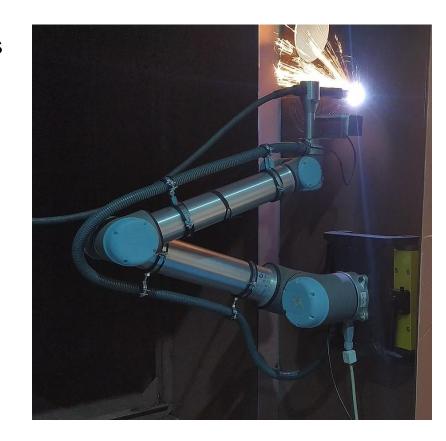


The technology

- Portable solution for plasma cut applications or different applications
- Required material:

Magnetic Base	Collaborative robot (UR10)
3D Camera (Intel RealSense d435i)	Plasma cut machine and torch

- Automatic robot localization with artificial vision
- Detect cutting plane and perform automatic trajectory
- Data acquisition and vertical integration for tradability
- Easy parameter configuration to perform cuts in different positions





The demonstration in the shipyard



MARI4YARD

Demonstration in the shipyard: Objectives

- 1. Put a pipe on the performed cut with less corrections
- Demonstrate robot portability





This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement n^{o} 101006798.



COLLABORATIVE ROBOTS: Plasma Cut Application Hardware deployment and electrical connections











Demonstration in the shipyard: Objectives

3. Demonstrate easy deployment

4. Vertical integration of process (tradability)

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COLLABORATIVE ROBOTS: Plasma Cut Application Software sequence and GUI









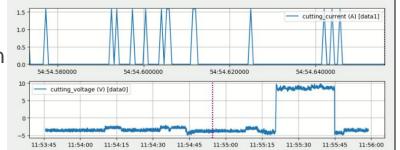








Voltage, Current, Robot position







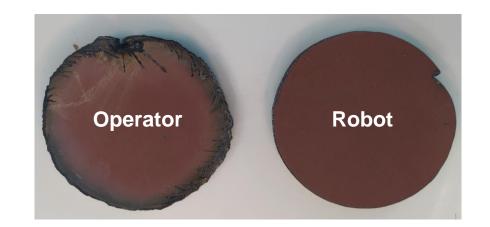
The impact for the shipbuilding industry





Impact for the shipbuilding industry

- Reduce number of operations during cut with cleaner results
 - Operator (3)
 - Robot (1)
- Reduce total time for operation
 - Operator (8:45 min)
 - Robot (7 min) (20% time reduction)
- Cut accuracy of 5 mm
- Perform previous tasks before shipyard manufacturing





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