



February 15th WORKSHOP

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3D Points Cloud

3D Scanner

- Training is required to make the scans.
- Slow data capture (4-10 min per scan)
- Assembly process carried out by hand (20 scans 20h).
- Possibility to export as cloud, mesh, whole scan, part of a scan, 3D viewer, etc.
- The generated 3D points cloud is very accurate (1mm).

Photogrammetry

- It is not necessary a previous training to use the camera.
- Quickly data capture (30-40 seg per scan)
- Automatic assembly is given by the camera supplier. (20 scans 12h).
- Visual results only. These results can be exported as a points cloud file (.xyz).
- The 3D points cloud is not very accurate as it is generated from photos (a few cm).

LIDAR

- A short training is necessary to use the scanner.
- Quickly data capture (in 20 minutes it is possible to scan around 250).
- The supplier's software makes assembly automatic.
- A 3D points cloud is obtained.
- The generated 3D points cloud has an accuracy of 2-3cm.

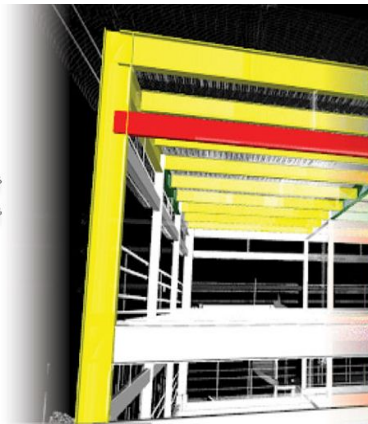


Our Targets

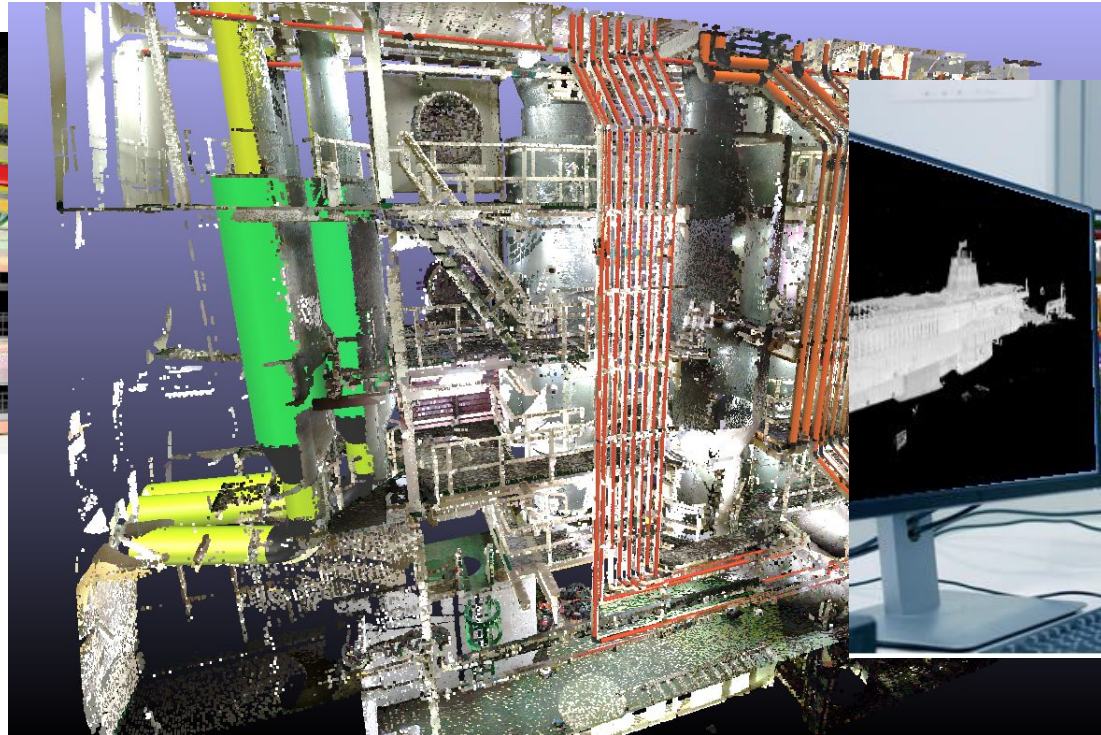
1. Progress Monitoring
(Task 10.21)

2. Reverse Engineering
(Task 13.25)

3. Project Documentation
Updating
(Task 14.26)



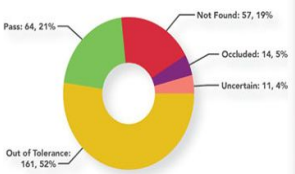
New building & retrofit



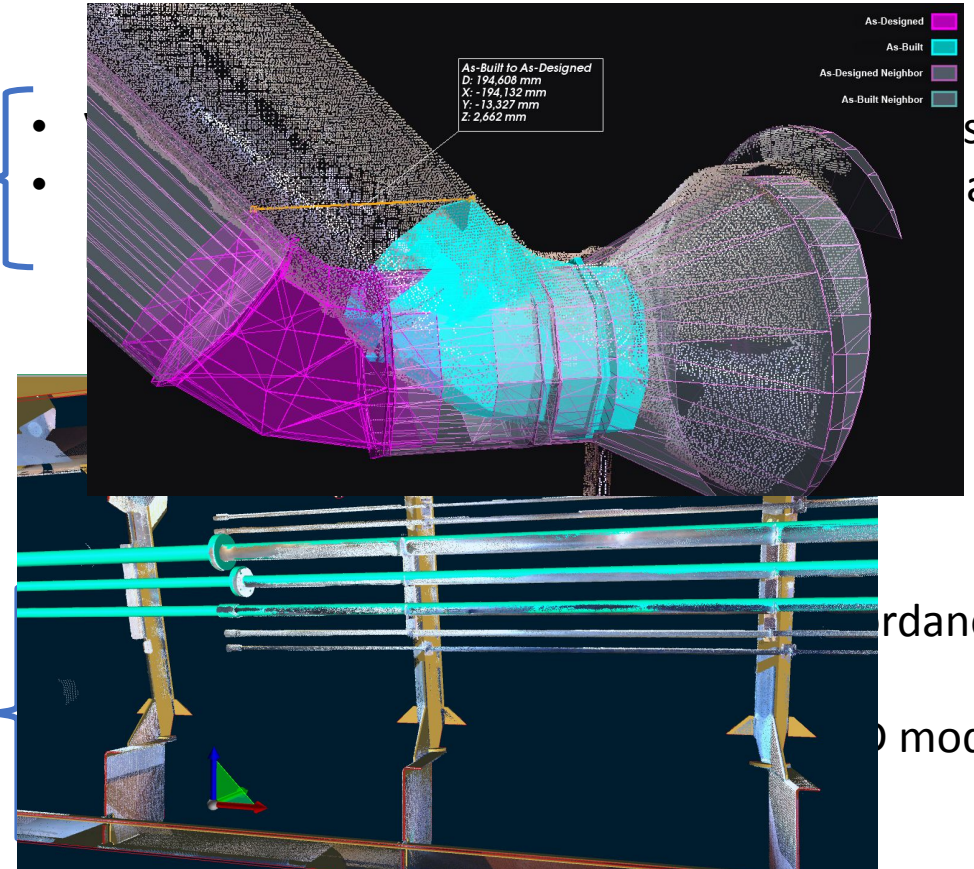
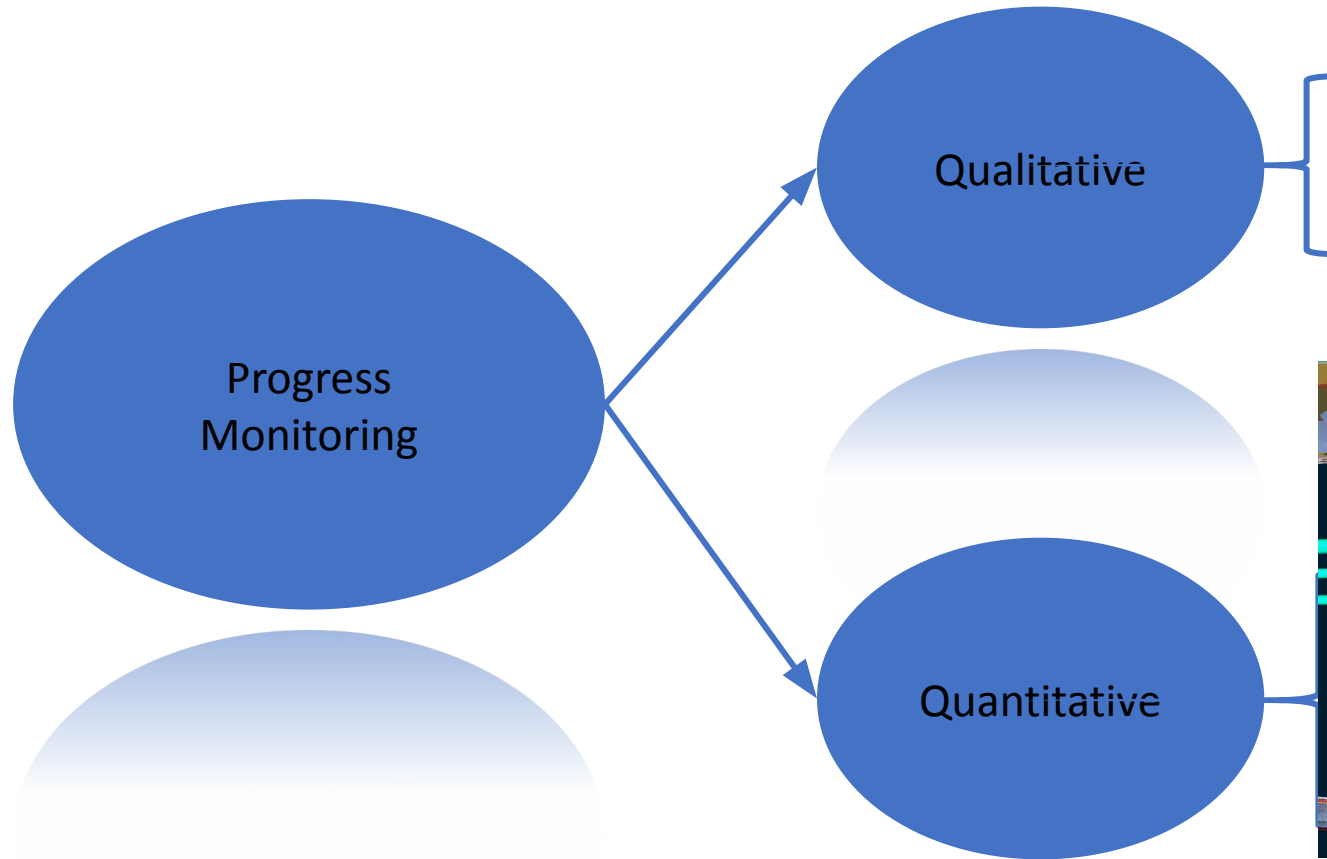
New building & retrofit



New building & retrofit



1. Progress Monitoring



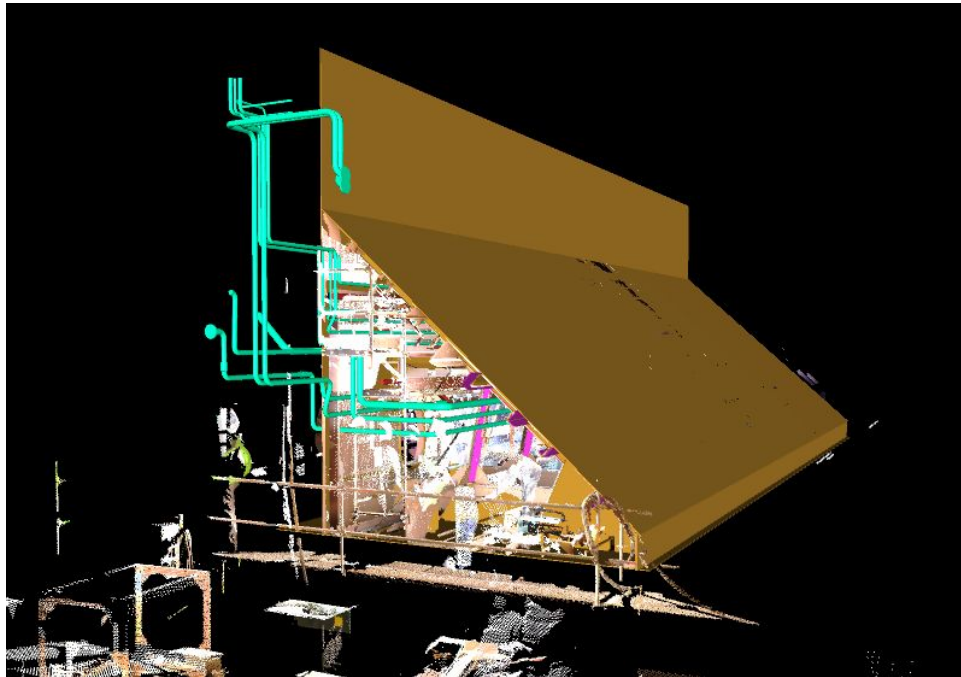
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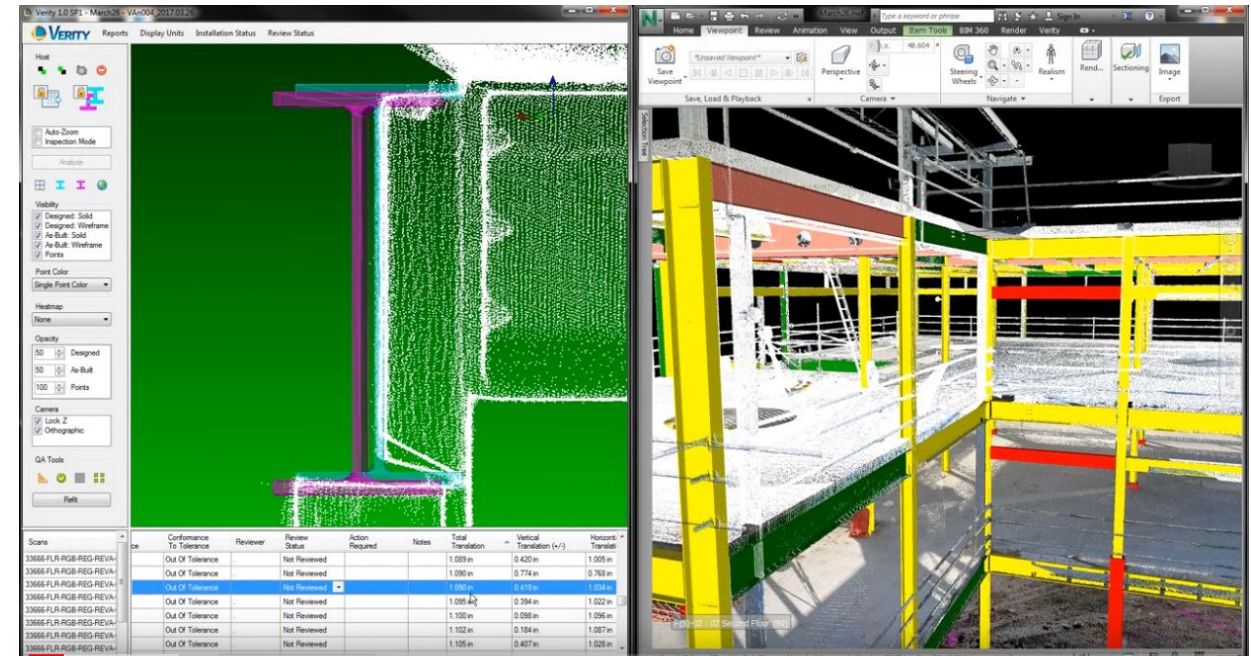
1. Progress Monitoring

Compare the real position of equipment with the 3D model by 3D scanning

Visual method (Navisworks)

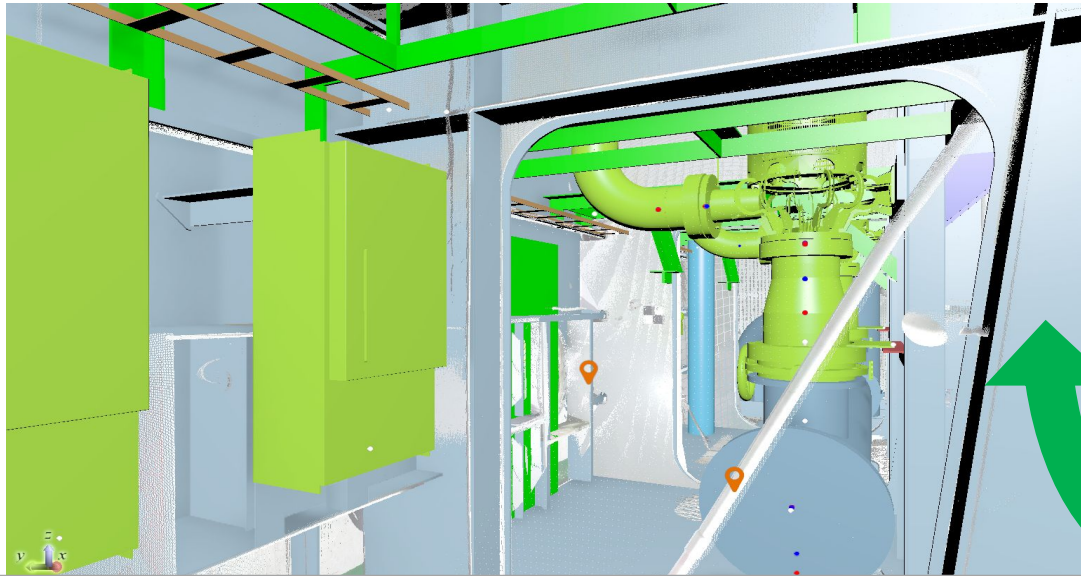
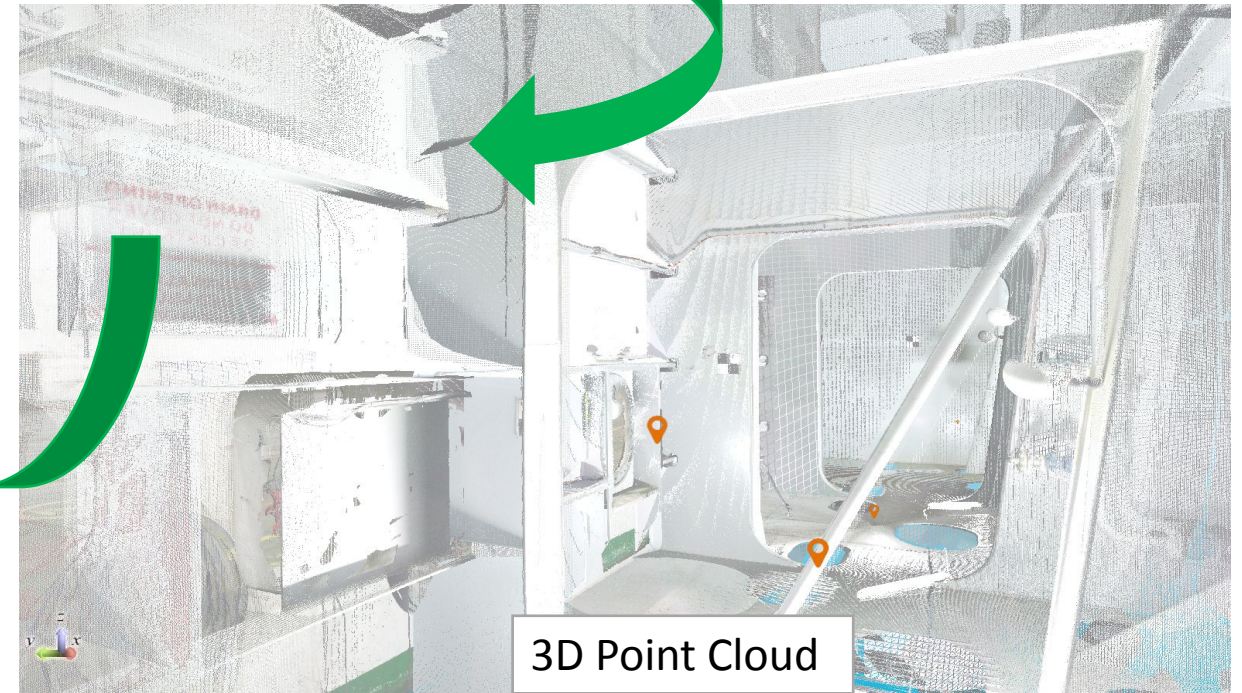
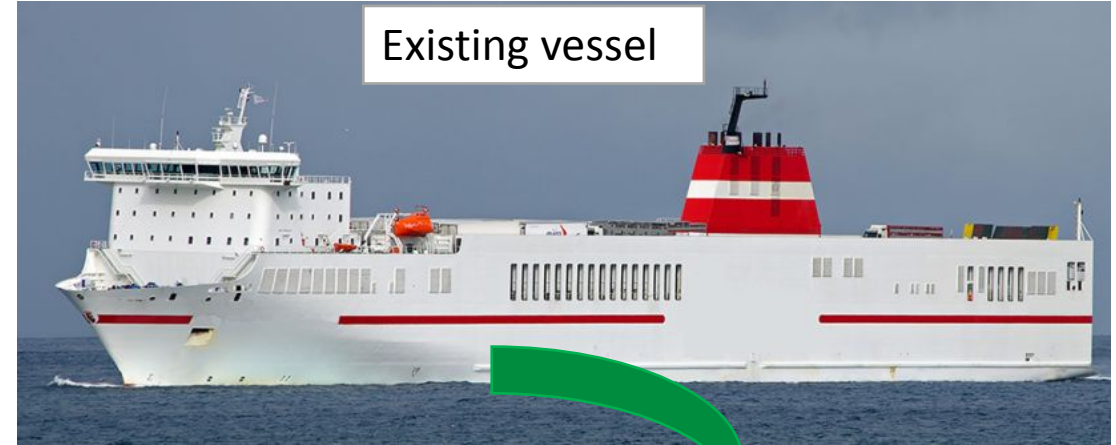


Automated method (Verity+Navisworks)



Score	Conformance To Tolerance	Reviewer	Review Status	Action Required	Notes	Total Transition	Vertical Transition (1/2)	Horizont-Transition
33666.FLR.RGB-REG-REVA	Out Of Tolerance		Not Reviewed			1.089 in	0.422 in	1.005 in
33666.FLR.RGB-REG-REVA	Out Of Tolerance		Not Reviewed			1.090 in	0.774 in	0.763 in
33666.FLR.RGB-REG-REVA	Out Of Tolerance		Not Reviewed			1.090 in	0.470 in	1.034 in
33666.FLR.RGB-REG-REVA	Out Of Tolerance		Not Reviewed			1.090 in	0.394 in	1.022 in
33666.FLR.RGB-REG-REVA	Out Of Tolerance		Not Reviewed			1.100 in	0.088 in	1.096 in
33666.FLR.RGB-REG-REVA	Out Of Tolerance		Not Reviewed			1.102 in	0.184 in	1.087 in
33666.FLR.RGB-REG-REVA	Out Of Tolerance		Not Reviewed			1.105 in	0.407 in	1.028 in

1. Existing Vessel
2. 3D points cloud of the vessel
3. Model based on the 3D points cloud
4. Modification of existing elements or addition of new ones



3D model based on the 3D points cloud with modifications

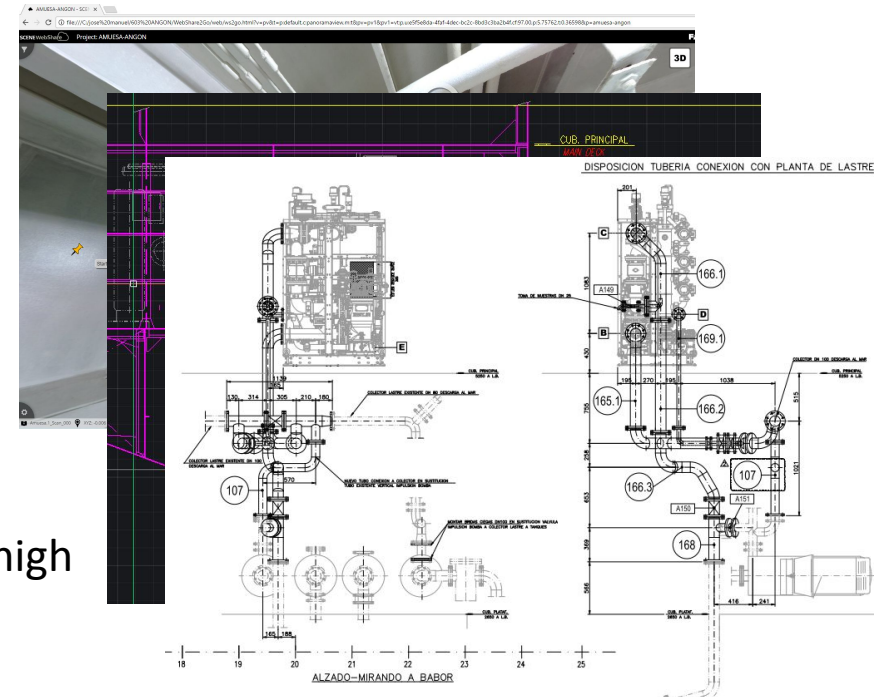
Points cloud viewer + 2D software



Steps:

- Measurements from an scan viewer (3-coordinates X,Y,Z) to place the elements in the different views of the drawing.
- Position the above measurements in the different views to obtain the initial drawing to start the retrofitting.
- Once the existing is represented, the modifications necessary for retrofitting are added and the construction drawings are created manually.

The accuracy of this method is not very high

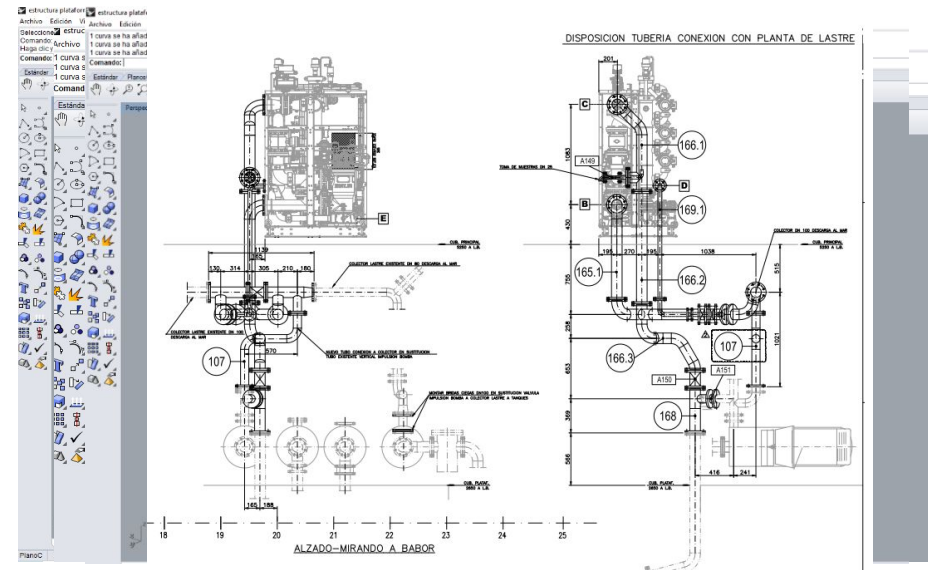


Point cloud viewer + 3D generic software



Steps:

- Import points cloud into the 3D software.
- Adding new elements needed to begin the work like new equipment or new structures for example.
- Execute the work taking into account the points cloud (in blue new pipelines).
- Obtain manually the construction drawings.



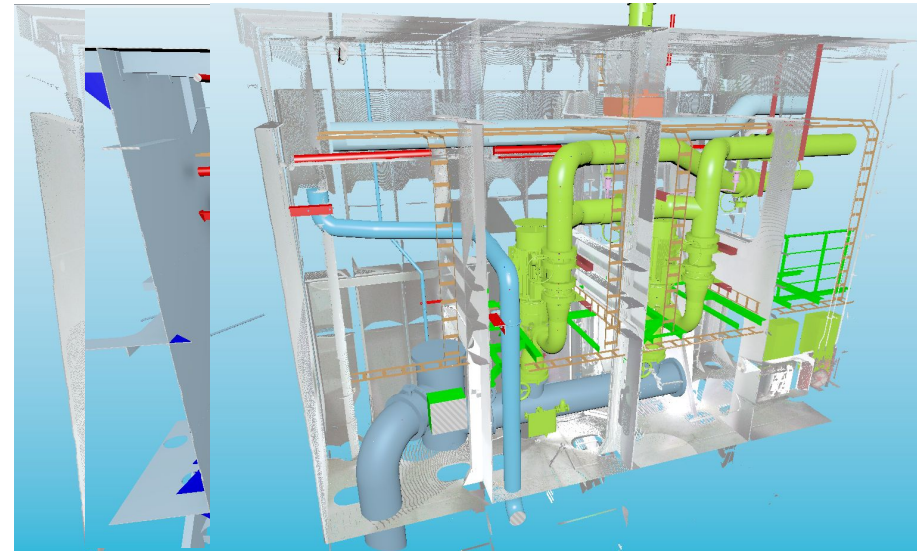
In this case, the advantage is that connections with the existing elements can be seen in 3D and all the clashes that may occur while designing can be detected. Therefore, with this procedure the start of work is faster and the results are more accurate than the previous procedure.

Points cloud viewer + 3D specific software



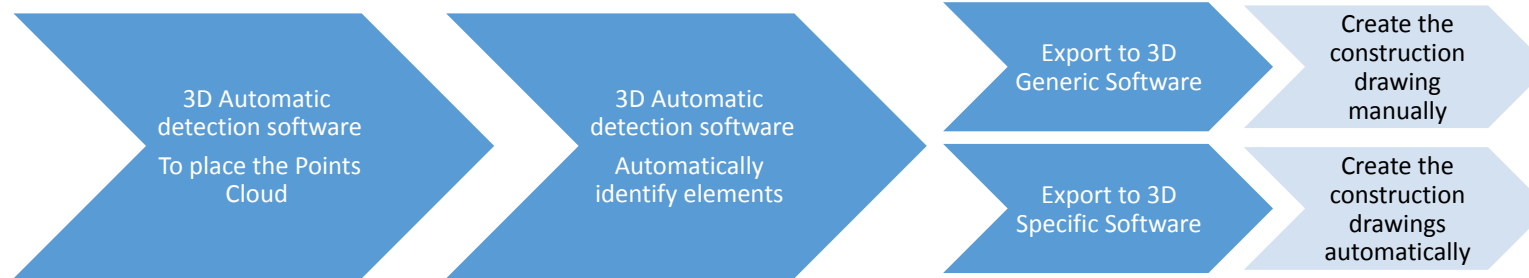
Steps:

- Import points cloud into the 3D software.
- The new piping is routed and the necessary structure is modelled, as well as modelling of the cable trays, platforms and position the new equipment.



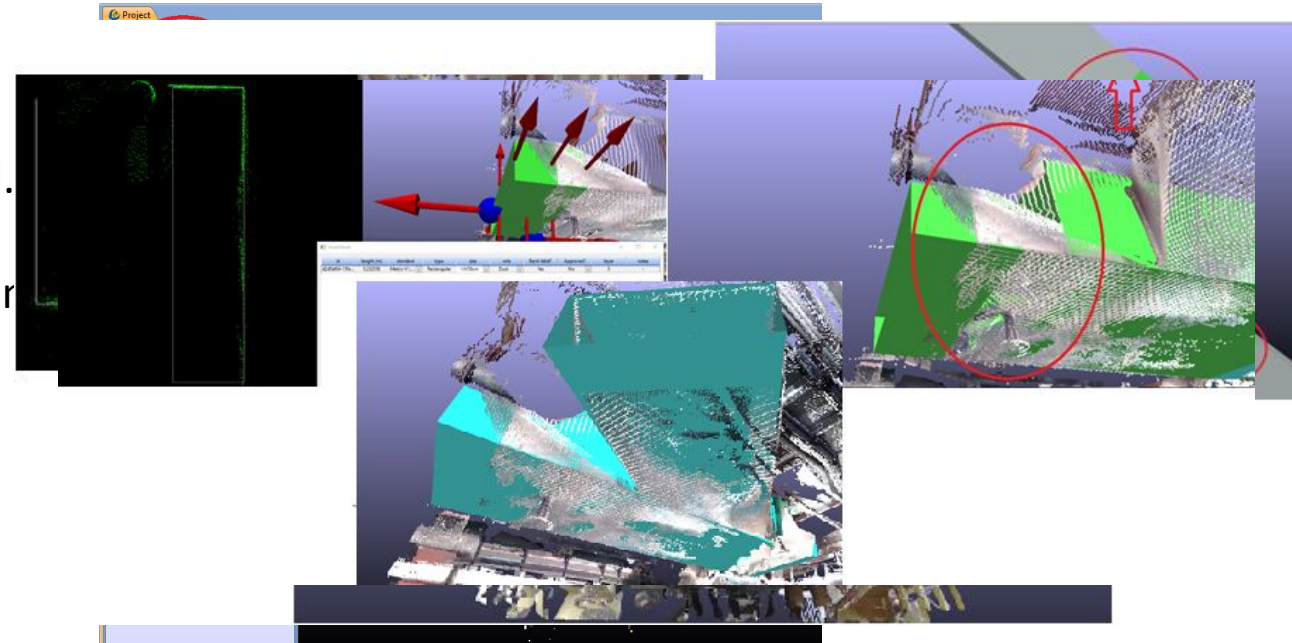
In this case, the advantage is the software since is an specific software to the shipbuilding industry, the tools for the modelling of pipes, structure, etc. are adapted and their use is much faster and easier to perform.

Points cloud + 3D automatic detection software



Steps:

- Insert the points cloud into Edgewise.
- Structured and unstructured points cloud can be inserted.
- Straight pipe sections are identified automatically and structures, gutters, ventilation ducts can be identified manually.
- Export to programs such as Rhinoceros (geometry) or to programs such as Aveva or Cadmatic (geometry with attributes).



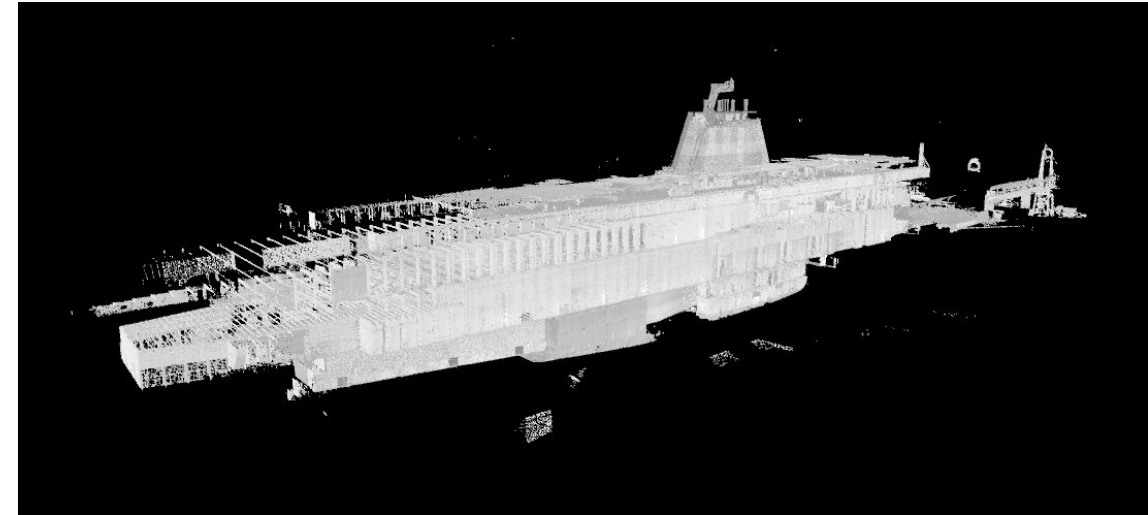
In large projects it can be a great time saver to identify elements

Depending on the purpose of the project documentation, different procedures can be done with different tools.

1. Virtual model only for visualisation or taking measurements.

Photogrammetry

2. Updating of documents based on the constructed vessel.



Updating during construction → Project monitoring

Updating at the end of construction.
Depending on the work to be carried out, a different level of precision will be required.

Tasks that do not involve a great precision, such as updating the arrangement of equipment in a room. → Photogrammetry or LIDAR

Tasks that require high precision, such as drawing piping isometrics. → Fixed laser scan

A large volume of work with different accuracies.

→ Fixed laser scan + LIDAR

Thank you for your attention!



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